

THE CURRENT STATE OF RUSSIAN SPACE SURVEILLANCE SYSTEM AND ITS CAPABILITY IN SURVEYING SPACE DEBRIS

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ABSTRACT

A review is made on the stages of creation and the current state of Russian Space Surveillance System (RSSS), its information sources and information processing technology. The percentage of space debris in the trackable space objects (SO) catalogue is determined. Classification of RSSS-tracked SO is made and analysed. The RSSS capability for enlarging the trackable SO set in the area of small and weakly-contrasting SO is estimated.

1. INTRODUCTION

The idea of creating the SSS in the USSR arose in 1961 and first real space surveillance was put into practice in 1962 by the information from optical facilities of the Academy of Sciences and of the Department of Defence.

In 1969 the Space Surveillance Center (SSC) was created for performing these functions. In 1970 the SSC was keeping close track of 200-250 SO (10-15% of the total amount of SO in orbit) by information of optical stations and of the first specimens of radar sensors of the Ballistic Missile Early Warning System (BMEWS) and the Anti-Ballistic Missile Defence (ABMD). By 1975 the number of trackable SO had already exceeded 1000, for 80% of them the SO position determination temporal error along the track having been less than 2 s.

During the subsequent years building up the sensors net continued (first of all of the radar ones) and the data processing methods had been improved.

2. RSSS'S CAPABILITIES

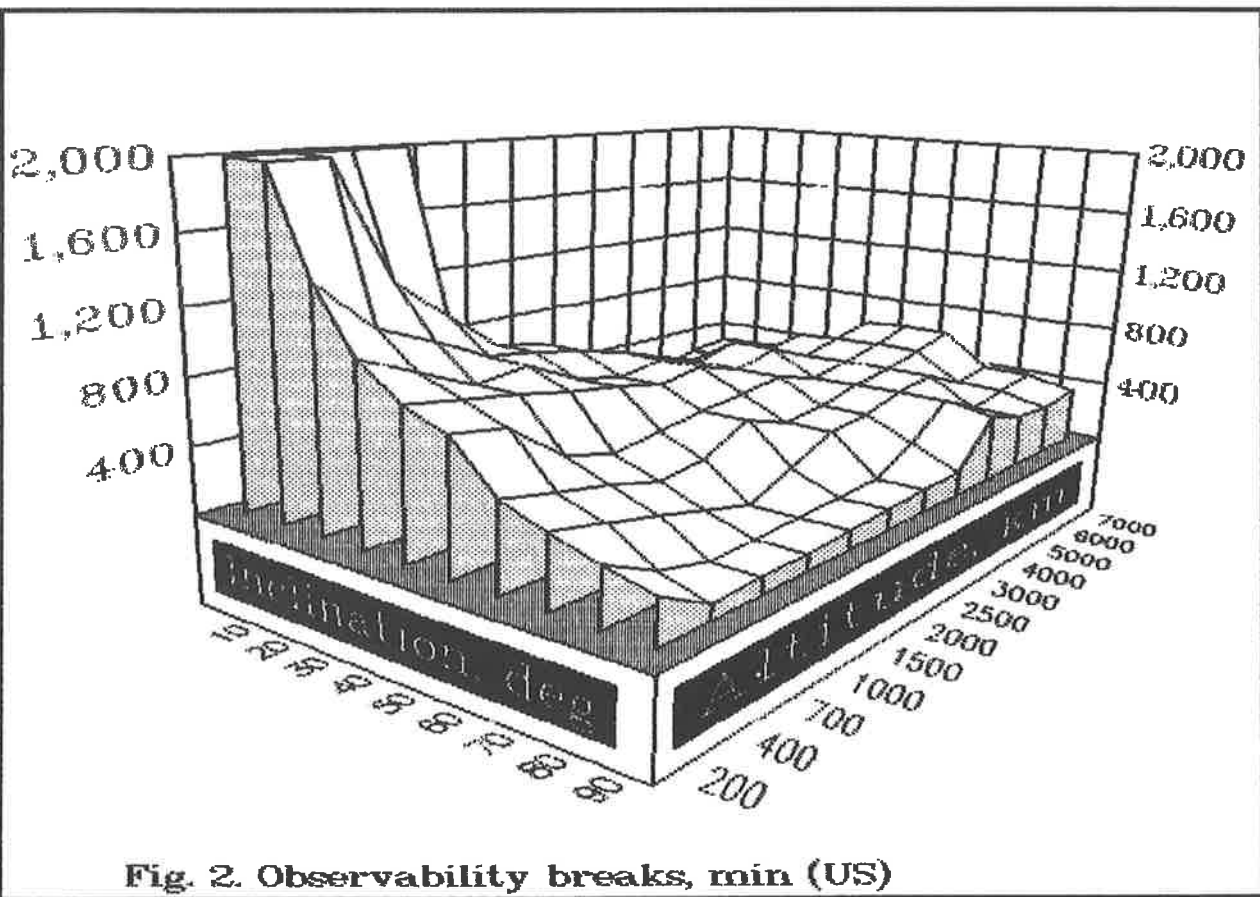
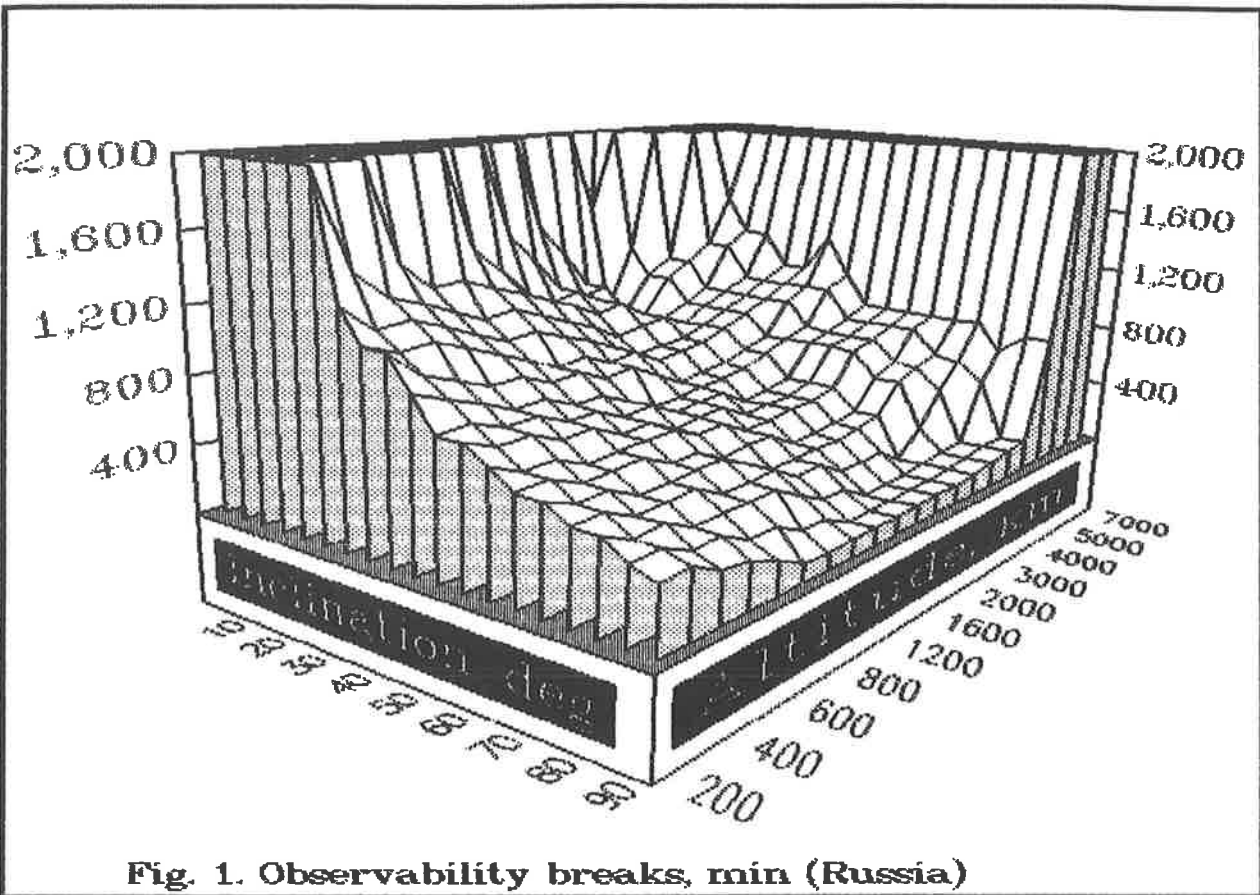
So at the present time the primary data acquisition system of the RSSS includes the net of radars (Table 1) and the net of optical sensors (Table 2). And also some other sensors may be enlisted occasionally.

Location	Operating system	Coordinates of site	Azimuth coverage	Observing band
Irkutsk Russia	BNEWS	103 E 53 N	30-300	VHF
Balkhash Kazakhstan	BNEWS	74 E 45 N	30-330	VHF
Murmansk Russia	BNEW	40 E 68 N	295-355	VHF
Riga Latvia	BNEWS	22 E 57 N	220-310	VHF
Sevastopol Ukrain	BNEWS	33 E 44 N	140-260	VHF
Uzhgorod Ukrain	BNEWS	23 E 48 N	165-285	VHF
Petchora Russia	BNEWS	57 E 65 N	300-0-55	VHF
Mingechaur Azerbaijan	BNEWS	48 E 41 N	105-215	VHF
Moscow Russia	ABMD	37 E 55 N	255-305 65-120	UHF

Table 1. RSSS radar sensors

Unlike the SSM of the USA all the sensors of the RSSS are located only at the former USSR territory. Hence, relatively great interruptions in observation and some "invisibility" zones are peculiar to the RSSS. Figs. 1 and 2 represent the simulated SO observability breaks distribution depending on orbit inclination and altitude for the both SSS - Russian and American. One can see the difference in favour of the last one.

To provide the high quality of performing space



surveillance functions in such circumstances we have been forced to give particular attention to the development of measurement processing theory, methods and technique.

Location	Coordinates of site	Azimuth coverage	Type
Irkutsk (Russia)	100 E 52 N	0-360	Electro-optical
Kiev (Ukraine)	30 E 50 N	0-360	Optical
Uzhgorod (Ukraine)	22 E 49 N	0-360	Optical
Dushanbe (Tadjikistan)	69 E 39 N	0-360	Optical
Alma-Ata (Kazakhstan)	77 E 43 N	0-360	Optical
Abastumani (Georgia)	37 E 56 N	0-360	Electro-optical
Burokan (Armenia)	44 E 40 N	0-360	Electro-optical
Zvenigorod (Russia)	37 E 56 N	0-360	Optical
Simeiz (Ukraine)	34 E 44 N	0-360	Electro-optical
Uzhno-Sakhalinsk (Russia)	143 E 47 N	0-360	Optical
Ashgabad (Turkmenia)	58 E 38 N	0-360	Electro-optical
Kourovka (Russia)	60 E 57 N	0-360	Optical

Table 2. RSSS optical sensors

As a result a good space ballistic school was originated. One can judge about its scientific level by the results of well known emergency works on the reentry stage of flight of the satellites "Cosmos-954" (1978), "Skylab" (1979), "Cosmos-1402" (1983), on informational provision of docking the transportation spacecraft "Soyuz-T-13" and the orbital station "Salyut-7" (1985) and, finally, monitoring the last stage of flight of the orbital complex "Salyut-7"-"Cosmos-1686" (1991).

The information from all the sensors mentioned is transmitted to the SSC. The measurements are identified there, then they are used for updating the

cataloged SO orbital parameters. Measurements not related to any cataloged SO are being collected and then are used for detecting new SO orbits or for recovering the "lost" SO orbits.

On the base of the SO catalog there are performed planning the observations, calculation of the initial data for subsequent SO observations, calculation of SO orbit life-time and the area of its reentry, and preparing and delivery of information to the consumers. The structure of information processing in the SSC is presented in Fig. 3. Some characteristics of the RSSS on March 1993 are shown in Table 3.

Total number of cataloged SO	7500
Number of breakup SO fragments	2450
Number of payloads	2000
Daily number of measurements	40000
Percentage of identified measurements	99%
Number of orbit updates per day	10000
Daily number of new orbits	7 - 10
SO position determination mean square error at the time of the last measurement:	
along track	4.5 km
radial component	1.5 km
binormal component	0.8 km
SO decay time determination error when the time to decay is less than	
1 day	< 4.5%
2 day	< 8%
30 days	< 10%

Table 3. Characteristics of SSS on March, 1993

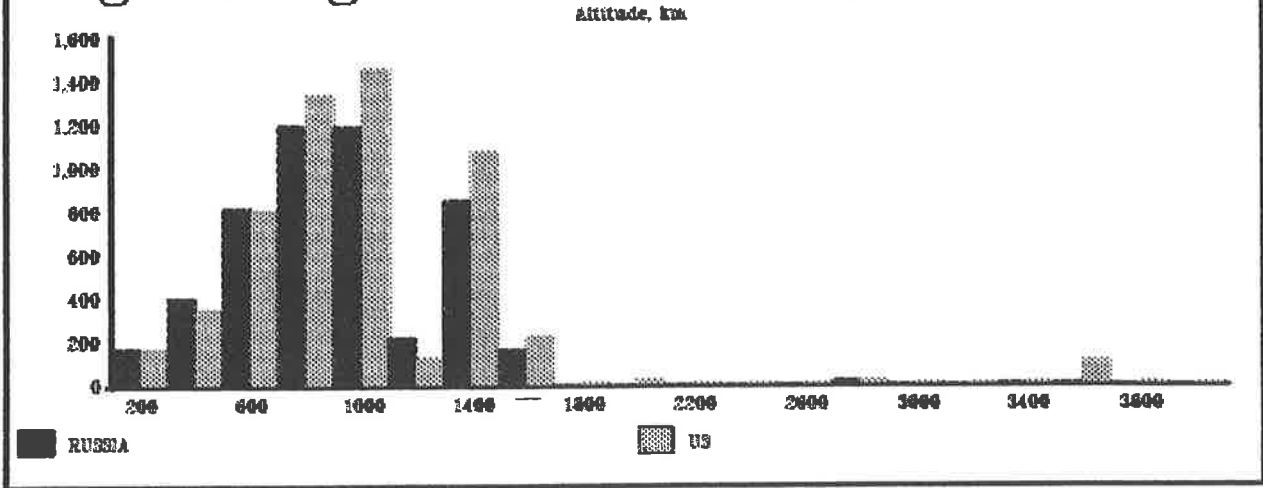
Figs. 4 and 5 display the cataloged SO distribution at the RSSS and the American SSM depending on perigee height (for altitudes less than 4000 km) and inclination. It can be seen that for inclinations from 60 to 100 degrees the American catalog contains by 850 objects more than the Russian one, but for inclinations less than 25 - by 160 SO less than the Russian catalog. This divergence is conditioned first of all by different technical characteristics of tracking facilities used, their locations and also by different criteria of putting SO orbit data into the catalog and taking them out of it.

The RSSS catalog comprises about 7500 SO, some 2000 of them being payloads (operating or dead).

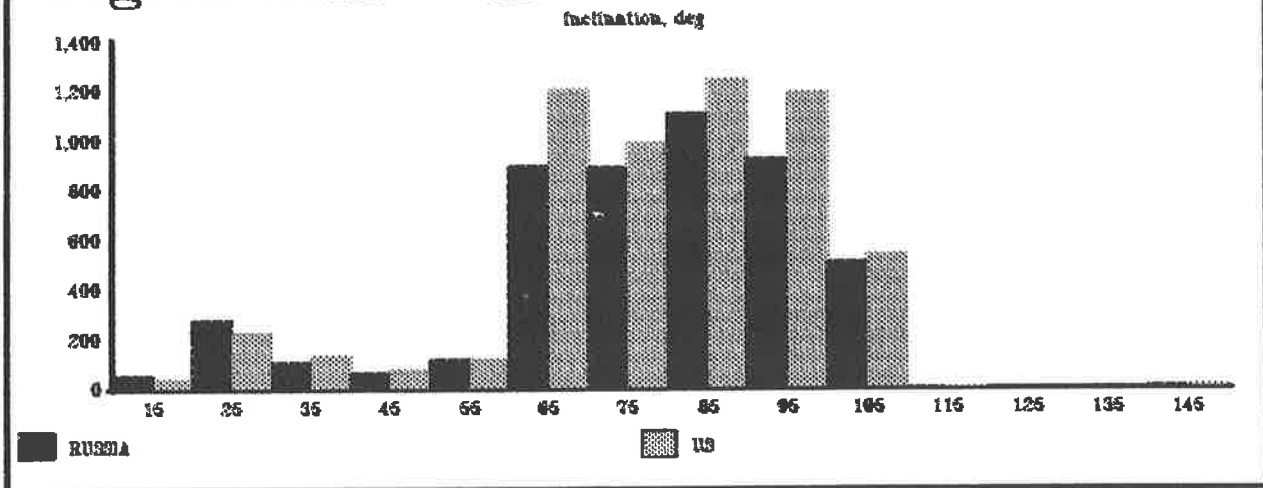
Fig. 6 illustrates the RSSS capability of detecting SO breakup fractions, taking an example by "Cosmos-2227" upper stage breakup on Dec. 26, 1992. There is shown fragments catalogation dynamics after the SO breakup in integral and differential forms.

The RSSS as well as the American one was not designed

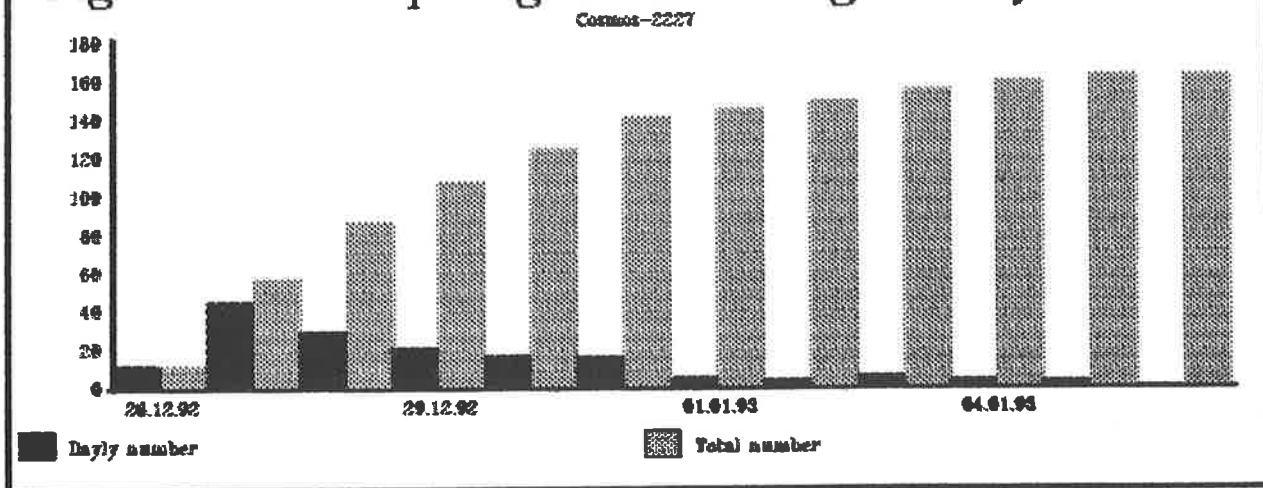
**Fig. 4 Perigee altitude distribution of SO**



**Fig. 5. Inclination distribution of SO**



**Fig. 6. SO breakup fragments catalogation dynamics**



for observing small objects. And that is the sore spot, susceptibilities of the both SSS while concerning their capabilities in surveillance of space debris.

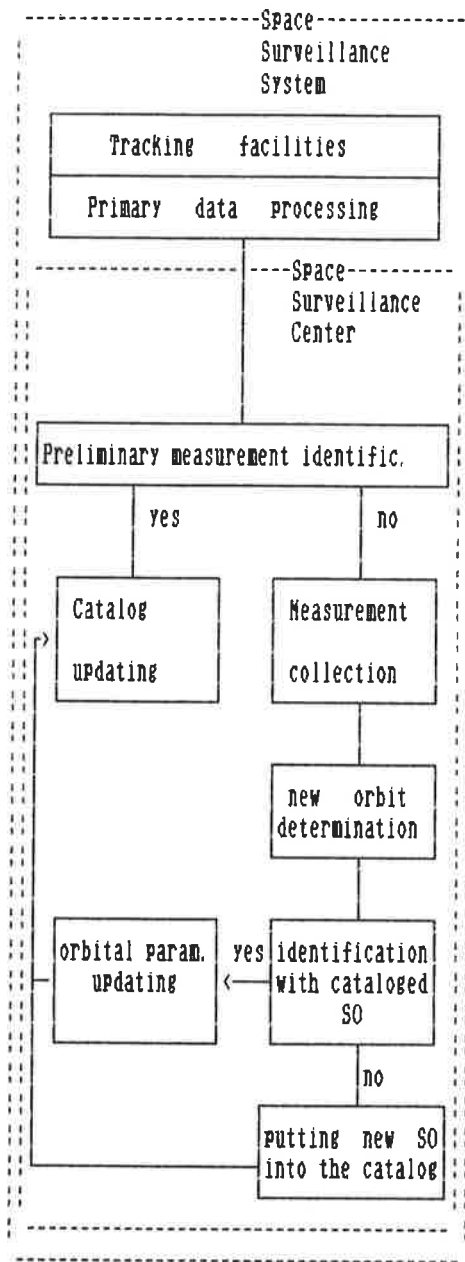


Fig. 3. Automatic data processing in the SSS

With the aim of overcoming this obstacle in the RSSS investigations are being carried out in the following areas:

- lowering the radar's operational sensitivity thresholds;
- creating the special ground based facilities for detection of small SO;
- development of special methods for acquisition of a weak useful signal, using a-priori information on the SO motion, with the help of narrow-angle and narrow-beam sensors.

As to the first direction, 5 experiments with a radar in UHF-band were conducted, duration of each being up to an hour. The following preliminary results were obtained. When lowering the sensitivity threshold by 2.5 dB and taking some measures for mitigation of interferences, the measurement flux increased by 2.7 times and the total number of detected 10 cm particles increased by several times. The experiments will continue.

The second direction is being assimilated by for example Dr. Tolkathev from SRI of Radiophysics in Moscow.

As to the third direction, a special report is dedicated to it here later.

### 3. OFFERS FOR COOPERATION

Sharing the concern of international scientific community about increasing contamination of space, Russia in the person of the SRC "Kosmos" is ready to cooperate in the following areas:

1. Informational support of space programs and experiments of concerned countries.
2. Coordinated operations in contingencies and notification of the concerned countries about dangerous situations in space and out of space.
3. Control of international agreements related to legal issues of using the near Earth space.
4. Informational provision for research on the upper atmosphere density variations.
5. Ecological monitoring of the near Earth space (space contamination control and analysis of its consequences).
6. Scientific provision of business cooperation mentioned above.