Analysis of tracking and orbit estimation results of Korean space debris on LEO using the optical and the radar data

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ABSTRACT

Since 1992, 15 satellites on Low Earth Orbit (LEO) and nine satellites on Geostationary Earth Orbit (GEO) have been launched as Korean space asset into the Earth orbit. As of 2018, two satellites on LEO and four satellites on GEO are under operation. An optical tracking simulation results of Korean inactive satellites on LEO were analyzed in this research. And also the tracking and orbit estimation results were analyzed for the first Korean space debris, KITSAT-1, with the radar measurements. The orbit estimation results were compared with the Two Line Elements by Joint Space Operation Center of the United States. The optical tracking facility for the simulation was the OWL-Net (Optical Wide-field patrolL-Network). The OWL-Net is a global optical tracking network for SSA in Korea. The radar data was provided from the LeoLabs radar network.

1 INTRODUCTION

In 1992, KITSAT-1 was launched for a collaborative research mission. KITSAT-1 was based on the modular microsatellite bus. An altitude of KITSAT-1 was designed by about 1300 km above the ground. It was a first Korean artificial satellite. In 2019, among 43,931 registered space objects, 27 space objects are distinguished as Korean space assets. Except decayed object and rocket body, 23 space objects orbit around the earth [1]. Earlier launched Korean space objects on low earth orbit (LEO) had bigger semi-major axis. Therefore, almost Korean space debris on LEO have too high altitude to re-enter the ground in the near future. In case of inactive satellites of geostationary earth orbit (GEO), de-orbit process was done after the end of mission. Koreasat-1, 2 was de-orbit to the graveyard of the GEO.

In Tab. 1., summary of Korean space assets is described. The three space objects launched by the university were neglected. Among 12 LEO satellites, eight satellites are inactive now. Furthermore, some GEO satellites ready to close their mission.

Table 1. Summary of Korean space assets. Inactive satellites display as gray. Among 12 LEO satellites, eight satellites are inactive in 2019.

<table>
<thead>
<tr>
<th>Name</th>
<th>INTLDES</th>
<th>Apogee (km)</th>
<th>Perigee (km)</th>
</tr>
</thead>
<tbody>
<tr>
<td>STSAT 2C</td>
<td>2013-003A</td>
<td>528</td>
<td>259</td>
</tr>
<tr>
<td>KOMPSAT 3A</td>
<td>2015-014A</td>
<td>538</td>
<td>521</td>
</tr>
<tr>
<td>KOMPSAT 5</td>
<td>2013-042A</td>
<td>554</td>
<td>552</td>
</tr>
<tr>
<td>NEXTSAT-1</td>
<td>2018-099BF</td>
<td>591</td>
<td>571</td>
</tr>
<tr>
<td>STSAT 3</td>
<td>2013-066G</td>
<td>616</td>
<td>582</td>
</tr>
</tbody>
</table>

The Optical Wide-field patroL-Net (OWL-Net) has been developed from 2010 for the tracking of Korean LEO satellites and the monitoring the GEO region. The OWL-Net consists of five global robotic telescopes. The main target of the OWL-Net includes not only the active LEO satellites but also the inactive LEO satellites to prevent the international space hazard by domestic space debris.

In this research, we analysed the visibility for Korean space debris on LEO by the OWL-Net. The orbit estimation results were analysed for KITSAT-1, first Korean space debris on LEO. A radar data from Leolabs was utilized for this work.

## 2 OPTICAL TRACKING FOR SATELLITES ON LEO

As we mentioned in previous section, the OWL-Net is global robotic telescope network. The OWL-Net has been installed in Mongolia, Morocco, Israel, the United States, and South Korea. Each station has weather sensor to decide the observability. The observation was performed by daily schedule from head-quarter in South Korea. All five stations are in northern hemisphere [2].

![The location of the OWL-Net. Five stations are evenly distributed as longitudinal direction. However, the sites are only located in the northern hemisphere.](image)

The visibility study was done to find reasonable site location in 2011. We concluded that the location under $+30$ degree of latitude was acceptable to track Korean LEO satellites. The stations were installed only in norther hemisphere as a result [3]. Currently, we found that there was seasonal condition of the visibility for last several years. In case of the optical tracking, the sun elevation condition and the lighting condition was required. There conditions make the observable period for LEO space objects.

![visibility of KOMPSAT-1 for the OWL-Net. The observation is only possible for several months in one year.](image)
objects without the seasonal condition, other stations in the southern hemisphere are needed to add in the OWL-Net.

3 RADAR TRACKING FOR KITSAT-1 AND ORBIT ESTIMATION

LeoLabs is a commercial provider of tracking for LEO space objects. There are two radar stations of LeoLabs. The first one is the Poker Flat Incoherent Scatter Radar (PFISR) and the other one is the Midland Space Radar (MSR). These radars are phased arrays without tracking equipment. PFISR is a two-dimensional phased array and MSR is a one-dimensional phased array. These two radars can cover 95% of LEO satellite in the space catalogue [5].

We made the orbit estimation for KITSAT-1 with the radar observation data from the LeoLabs. Both radar stations’ data were used in the orbit estimation process. We used the data from 1 January 2018 to 13 December 2018. For weekly orbit analysis, we separated the data in seven day increments. In 12th week, there was no data for KITSAT-1.

The orbit determination process was done using the sequential filter and smoother. Calibrated range and range-rate by LeoLabs were used to estimate the orbit. Because KITSAT-1 has altitude over 1300 km from the ground, we used CIRA 1972 atmospheric drag model. The gravity model, solar radiation pressure and third body effects also considered. We used two line elements (TLE) as a priori for the least square process. The forward sequential processing and backward smoothing processing was done with the results from the least square process.

There was no observation data in 12th week. However, in fourth week, only MSR made observation. During the entire time, PFISR has almost ten times much observations than MSR. Larger field of view (FOV) and higher latitudinal position of PFISR would have made the condition for much observation data.

Fig. 4 shows root mean square (RMS) of position uncertainty from the smoother process. Median value of In-track direction RMS of position uncertainty did not exceed 200 m. However, 14th, 45th, and 49th weeks’ results show greater values than others. It was caused by the leak of observation data, the error of a priori and unevenly distributed observation data. We used single TLE for a priori of each orbit estimation process. Each TLEs were published in the first day of the selected orbit estimation period. These position uncertainty peaks were eliminated for yearly orbit estimation process. Although In-track direction position uncertainty was increased threefold during 12th week, it was caused by the leak of the observations. During the entire period, In-track direction position uncertainty was not exceeded 200 m.

Fig. 3 shows the distributions of number of observation for KITSAT-1 by Leolabs. PFISR has almost ten times much observations than MSR.
The estimated orbits were compared with consecutive TLEs. In case of KITSAT-1, sometimes TLEs were published twice a day. However, sometimes there was no update for a week. Especially, during 12th and 13th week, three TLEs published and last two TLEs were used for comparison. However, those two TLEs were confirmed that inaccurate one by comparing the other TLEs. In Fig.4., the comparison result for 13th week was shown huge range difference than others. The bigger range differences for fourth and seventh week was caused by less observation data. Median range difference in RMS did not exceed 500 m.

However, yearly orbit estimation process shows constant range difference for a year except 12th and 13th week. The range difference in In-track direction did not exceed +1 km for other dates.

4 DISCUSSION

As the increasing number of space objects, safety of active satellites from collision with space debris is an urgent problem. Among about 20,000 space objects, only about 2,000 space objects is in active status. To avoid the collision between space objects, precise orbital information is needed.

The OWL-Net, optical tracking network, was developed for tracking Korean LEO satellites and monitoring GEO satellites. The main target of the OWL-Net includes eight Korean space debris on LEO. The OWL-Net consists five global stations which is evenly distributed in longitudinal direction. However, the visibility for Korean LEO satellites by the OWL-Net shows the seasonal changes. Therefore, more stations in southern hemisphere are needed for continuous tracking of Korean LEO satellites with the OWL-Net. On the other hands, radar system is not affected by the optical observation condition, therefore much observation chances are guaranteed.

We made the orbit estimation test for KITSAT-1, first Korean space debris on LEO, using the radar data from LeoLabs. The radar network consists of two stations in the United States. The orbit estimation test was done on a weekly basis. Median value of In-track direction RMS of position uncertainty did not exceed 200 m. The estimated orbits were compared with consecutive TLEs. As a results, range difference in RMS for In-track direction did not exceed 500 m for almost weeks. In yearly basis analysis, abnormal peaks for position uncertainty or range difference were eliminated. It indicated that the radar data can be maintained the orbital information for KITSAT-1 for a year.

The estimation target at lower altitude need to be utilized the orbit estimation for more representative results for LEO space objects. The atmospheric drag was a main perturbation for the space objects on LEO. And much objects on LEO orbits under 1000 km from the ground. And the additional analysis is needed for 12th week. During 12th week, there was no radar data and TLEs show huge errors. The analysis results can be used for analysis of the observation condition of radar system.

5 REFERENCES

Because KITSAT-1 has altitude over 1300 km from the ground,
6 FIGURES AND TABLES

Figures and tables can extend over two columns if required. Figure captions should be centred below the figures; table captions should be centred above the tables. Use full word ‘Figure 1’ or ‘Table 1’ in the caption. Use the abbreviation “Fig. 1” or “Tab. 1” in the text (even at the beginning of a sentence).

7 REFERENCES

Number citations consecutively in square brackets [1]. Refer simply to the reference number, as in [3]. Do not use ‘Ref. [3]’ or ‘reference [3]’ except at the beginning of a sentence: ‘Reference [3] was the first …’. The title of the book or of the journal should be in italic script. Further information is available in “How to reference a publication” at: http://www.esa.int/esapub/conference/references.pdf

7.1 Sample References


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9 SUBMITTING THE PAPER

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Figure 6. Space Debris 2009