Uncertainty Dispersion Analysis of Atmospheric Re-entry using the Stochastic Liouville Equation

Maren Hülsmann, MSc.

Deutsches Zentrum für Luft- und Raumfahrt e.V. (DLR) German Space Operations Center (GSOC)





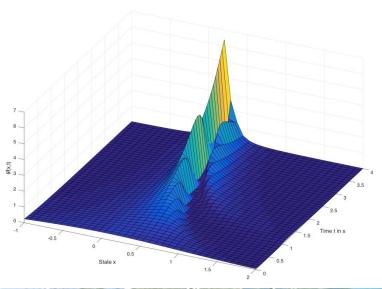
Outline

- Analyzing re-entry onto Earth is subjected to uncertainties
- Prediction of impact zone and its dispersion necessary
- Evolution of uncertainties in the initial conditions throughout the re-entry
- Stochastic Liouville Equation as alternative method for the Monte-Carlo Analysis
- Utilizing probability density functions (PDF)
- Solve PDF transport equation directly
- Comparison of results with reference dispersion generated by operational tool of GSOC (Monte-Carlo)



The Stochastic Liouville Equation

- Examine the development of the probability density of system dynamics over space and time
- Consider uncertainties in states and parameters
- From the resulting probability density function (PDF) all stochastic moments (e.g. covariance) can be deduced
- Non-linear model usable, no linearization needed





The Stochastic Liouville Equation

Consider a nonlinear state space model as following

$$\dot{X} = F(X)$$
, where $X = (x, p)^T \in \mathbb{R}^{n_X + n_p}$

The temporal evolution of probabilistic uncertainty is governed by

$$\frac{\partial \varphi(X,t)}{\partial t} + \sum_{i=1}^{n_X} \frac{\partial}{\partial X_i} [\varphi(X,t)F_i(X)] = 0$$

Stochastic Liouville Equation

Quasi linear partial differential equation (PDE) depending on the joint PDF



The Stochastic Liouville Equation

• the PDE can be reduced to an ordinary differential equation (ODE)

$$\frac{d\varphi(X,t)}{dt} = -\varphi(X,t) \sum_{i=1}^{n_X} \frac{\partial F_i}{\partial X_i}$$

which yields the solution

$$\varphi(X,t) = \varphi_0 \exp\left(-\int_0^t \sum_{i=1}^{n_x} \frac{\partial F_i}{\partial X_i} dX\right)$$

with the initial state and parametric uncertainties specified in terms of a joint PDF

$$\varphi_0 = \varphi(X, t_0)$$



Consider the four state model in case of non-rotating and spherical Earth

$$\dot{h} = v \sin \gamma$$

$$\dot{v} = -\frac{\rho}{2B_c} v^2 - g \sin \gamma$$

$$\dot{\gamma} = \frac{\rho}{2B_c} \frac{C_L}{C_D} v + \cos \gamma \left(\frac{v}{R_0 + h} - \frac{g}{v} \right)$$

$$\dot{\theta} = \frac{v \cos \gamma}{R_0 + h}$$

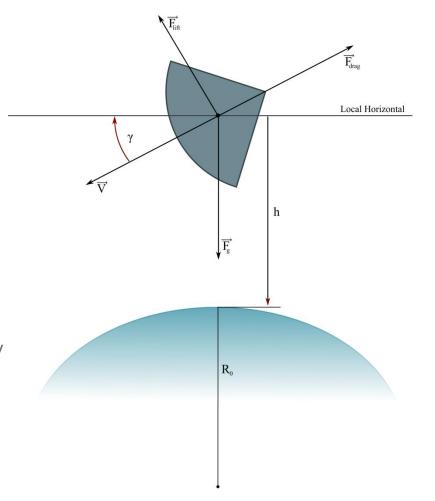
with

h Altitude g Gravitational field

ho Velocity ho Atmosphere density

Flight Path Angle (FPA) B_c Ballistic coefficient

9 Longitude $\frac{C_L}{C_D}$ Lift-to-Drag Ratio

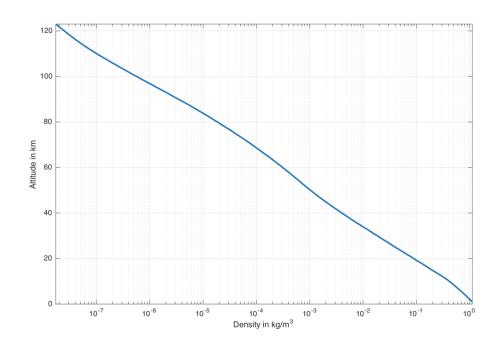




Example Re-Entry Trajectory

GSOC Re-entry model

- Gravity model
 - point mass
 (degree and order set to zero)
- · Sun and moon forces considered
- Atmosphere model
 - Jacchia-Gill (h ≥ 90km)
 - US Standard Atmosphere of 1976 (USSA76, h < 90km)



• For the use within the SLE, data of the Jacchia-Gill and USSA76 was interpolated



Example Re-Entry Trajectory

The three state model was extended by the Longitude along track.

$$\dot{\theta} = \frac{v \cos \gamma}{R_0 + h}$$

to determine the dispersion

S/C parameter:

Mass: 100 kg

 C_D : 2.3

 C_L : 0.0

Area: 1.0 m^2

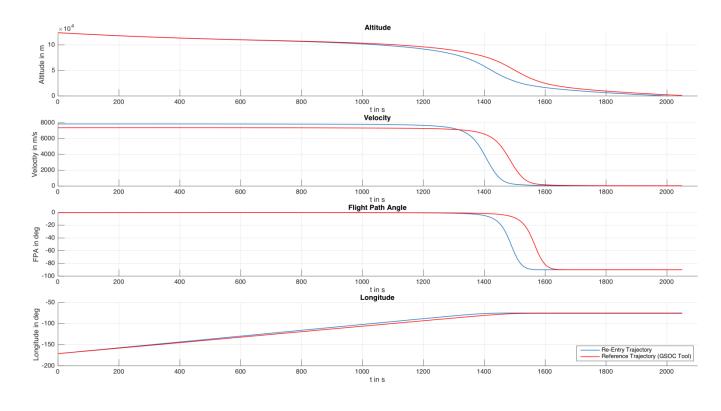
Initial conditions:

h₀ 123.996 km

 $v_0 = 7.8442 \, \text{km/s}$

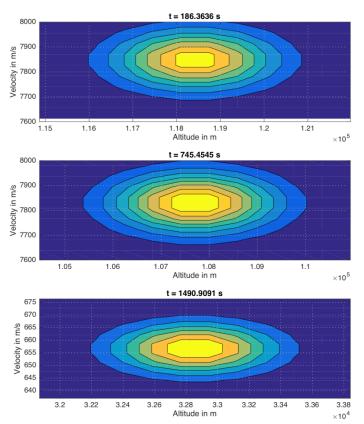
 γ_0 -0.243°

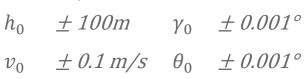
 θ_0 -171.11°

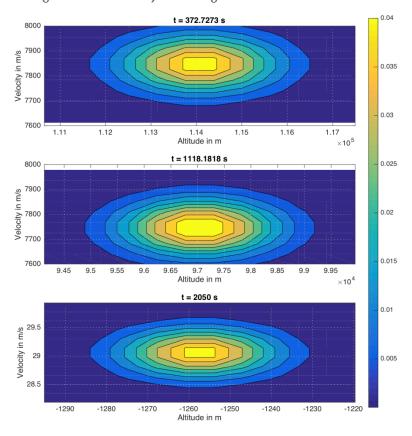




- Exemplary evolution of the two dimensional PDFs $\varphi(h, v)$
- The initial dispersions were chosen as:

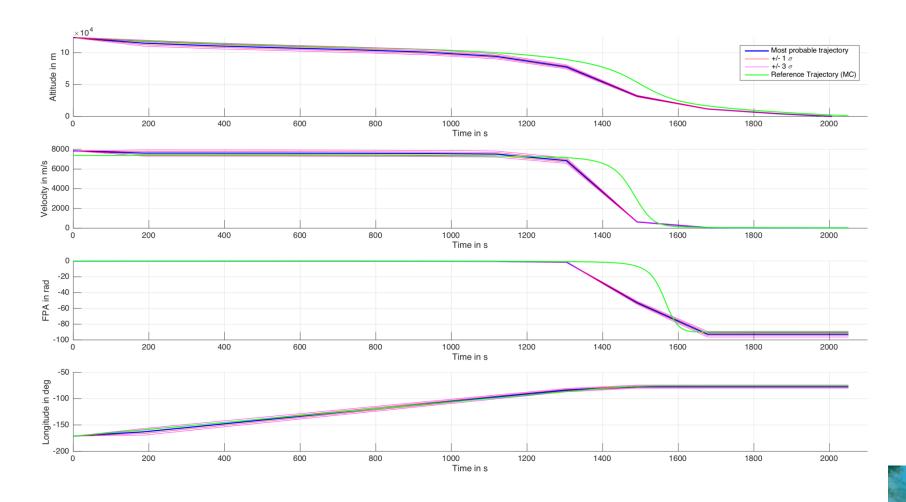






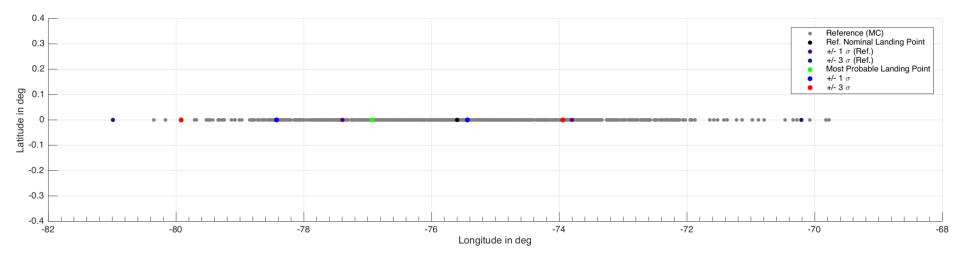


 Most probable trajectory generated from the PDFs in each time step in comparison with the reference trajectory



Landing Dispersion of Longitude in comparison with the landing dispersion of the reference run generated using the Monte-Carlo approach

	Results Stochas Liouville	tic Equation	Reference Monte- Carlo Analysis (GSOC)	
nominal	-76.93°		-75.6°	
σ	1.494		1.79	
$\pm 1\sigma$	-	-75.44°	-77.4°	-73.8°
±3σ	-	-73.94°	-80.9°	-70.21°





Summary and Conclusion

- The Stochastic Liouville Equation presents a computational efficient alternative for the Monte-Carlo Analysis
- Derive landing dispersions and footprints directly from PDFs
- The presented method was part of my master thesis at the University of Bremen in collaboration with DLR Institute of Space Systems in Bremen
- The shown example and reference trajectory/ dispersion was developed by DLR Space Flight
 Technology and Astronaut Training/ German Space Operation Center (GSOC)
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Any questions? Contact me via E-Mail: maren.huelsmann@dlr.de

